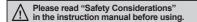
## **Area Sensor**

# ■ Features

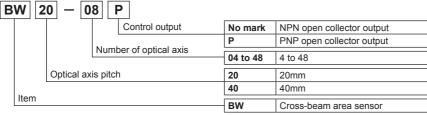
- Long sensing distance up to 7m
- 22 types of products
  - (optical axis: 20/40mm, sensing height: 120 to 940mm)
- Minimizes unsensing area with 20mm optical axis pitch (BW20-
- Easy to recognize at side, front, and long-distance by high brightness LED of Emitter and Receiver
- Includes self-diagnosis function, mutual interference prevention function, external diagnosis function.
- Protection structure IP65 (IEC standard)







# Ordering Information



## Specifications

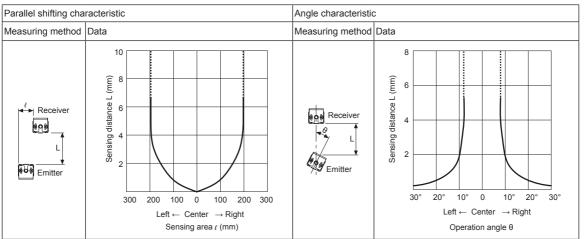
Model		BW20-□(P)	BW40-□(P)				
Sensing r	method	Through-beam type					
Sensing distance		0.1 to 7m					
Min. sens	sing target	Opaque material of min. Ø30mm	Opaque material of min. Ø50mm				
Optical a	xis pitch	20mm	40mm				
Number of	of optical axis	8 to 48	4 to 24				
Sensing I	neight	140 to 940mm	120 to 920mm				
Response	e time	Max. 10ms					
Power su	pply	12-24VDC== ±10% (ripple P-P: max. ±10%)					
Current c	onsumption	Emitter: max. 120mA, Receiver: max. 120mA					
Operation	n mode	Light ON fixed					
Control output		NPN or PNP open collector output  Load voltage: max. 30VDC= Load current: max. 100mA  Residual voltage - NPN: max. 1VDC=, PNP: max. 2.5VDC					
Protection	n circuit	Reverse polarity protection circuit, output short over current protection circuit					
Light source		Infrared LED (850nm modulated)					
Insulation resistance		Over 20MΩ (at 500VDC megger)					
Synchron	ization type	Timing method by synchronous line					
Self-diag	nosis	Emitter/Receiver monitoring, direct light monitoring, over current monitoring					
Interferer	nce protection	Interference protection by master/slave function					
Noise imr	munity	±240V the square wave noise (pulse width 1μs) by the noise simulator					
Dielectric	strength	1,000VAC 50/60Hz for 1 min					
Vibration		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours					
Shock		500m/s <sup>2</sup> (approx. 50G) in each X, Y, Z direction for 3 times					
Environ-	Ambient illumination	Ambient light: max. 100,000lx (receiver illumination)					
ment	Ambient temperature	-10 to 55°C, storage: -20 to 60°C					
ment	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH					
Protection	n structure	IP65 (IEC standard)					
Material		Case: aluminum,    Front cover, sensing part: acrylic					
Cable		Ø5mm, 4-wire, 300mm, M12 connector					
Accessor	у	Bracket A: 4, Bracket B: 4, Bolt : 8					
Approval		C€					
Weight*1		BW20-48: Approx. 2.1kg (approx. 1.4kg)	BW40-24: Approx. 2.1kg (approx. 1.4kg)				

X1: The weight includes packaging. The weight in parenthesis is for unit only.

D-44

<sup>\*\*</sup>The temperature and humidity of environment resistance is rated at non-freezing or condensation.

## ■ Feature Data



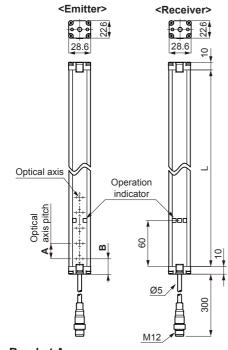
SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

# Dimensions



Model	L	A, B	Model	L	A, B
BW20-08(P)	160		BW40-04(P)	160	
BW20-12(P)	240	]	BW40-06(P)	240	]
BW20-16(P)	320		BW40-08(P)	320	
BW20-20(P)	400		BW40-10(P)	400	
BW20-24(P)	480		BW40-12(P)	480	
BW20-28(P)	560	20	BW40-14(P)	560	40
BW20-32(P)	640		BW40-16(P)	640	
BW20-36(P)	720		BW40-18(P)	720	
BW20-40(P)	800		BW40-20(P)	800	
BW20-44(P)	880	]	BW40-22(P)	880	

BW40-24(P)

960

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

> (C) LiDAR

(unit: mm)

#### (D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

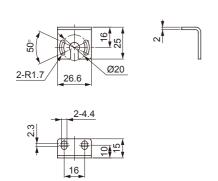
(G)

Pressure Sensors

(H) Rotary Encoders

(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

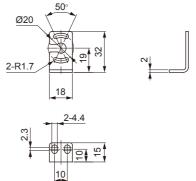
## Bracket A



#### Bracket B

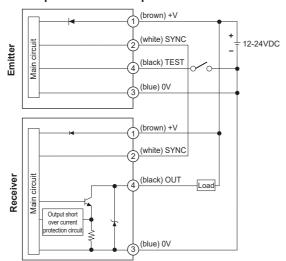
BW20-48(P)

960

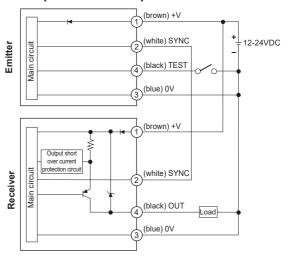


# **■** Input Output Circuit and Connections

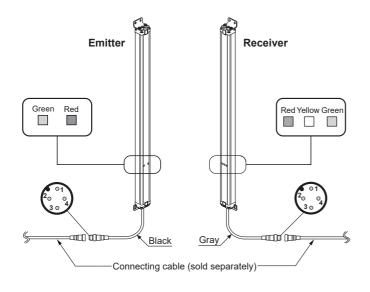
### • NPN open collector output



#### • PNP open collector output



# **■** Structure



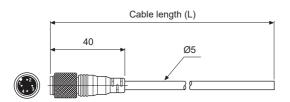
#### <Operation indicator >

LED color	Emitter	Receiver
Green	POWER	Stable light ON
Yellow	_	Unstable
Red	TEST (M/S)	Stable light OFF

#### <Wiring Connection >

Pin No.	Cable color	Emitter	Receiver
1	Brown	12-24VDC	12-24VDC
2	White	SYNC	SYNC
3	Blue	0V	0V
4	Black	TEST (M/S)	OUT

# **■** Connecting Cable (sold separately)



(unit:	

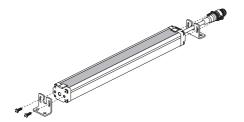
Туре	Model	L	Cable color
	CID4-3T	3m	
	CID4-5T	5m	
Emitter	CID4-7T	04-7T 7m B	
	CID4-10T	10m	
	CID4-15T	15m	
	CID4-3R	3m	
	CID4-5R	5m	
Receiver	CID4-7R	7m	Gray
	CID4-10R	10m	
	CID4-15R	15m	

\*\*Connecting cable is sold separately as one set; each of emitter's and receiver's.

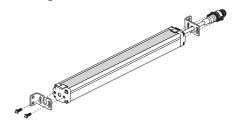
D-46 Autonics

# ■ Bracket Mounting

• Mounting the bracket A



• Mounting the bracket B



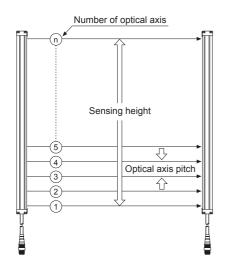
SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

# ■ Optical Axis Pitch/Number of Optical Axis/Sensing Height



Model	Number of optical axis	Sensing height	Optical axis pitch	Model	Number of optical axis	Sensing height	Optical axis pitch
BW20-08(P)	8	140mm		BW40-04(P)	4	120mm	
BW20-12(P)	12	220mm		BW40-06(P)	6	200mm	
BW20-16(P)	16	300mm		BW40-08(P)	8	280mm	
BW20-20(P)	20	380mm		BW40-10(P)	10	360mm	
BW20-24(P)	24	460mm	]	BW40-12(P)	12	440mm	
BW20-28(P)	28	540mm	20mm	BW40-14(P)	14	520mm	40mm
BW20-32(P)	32	620mm	]	BW40-16(P)	16	600mm	]
BW20-36(P)	36	700mm		BW40-18(P)	18	680mm	
BW20-40(P)	40	780mm		BW40-20(P)	20	760mm	
BW20-44(P)	44	860mm	]	BW40-22(P)	22	840mm	]
BW20-48(P)	48	940mm	]	BW40-24(P)	24	920mm	]

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LiDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

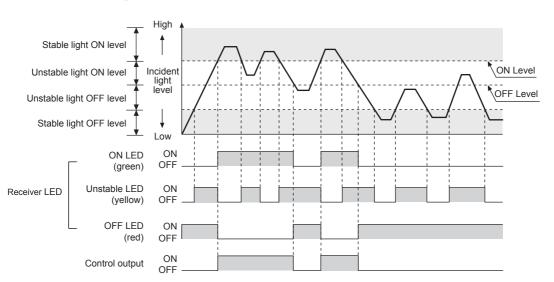
(G) Pressure Sensors

(H) Rotary Encoders

(I) Connectors/ Connector Cables/ Sensor Distribution

# **■** Operation Timing Diagram

• Operation mode: Light ON fixed

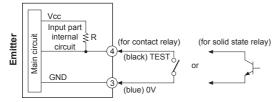


#### Function

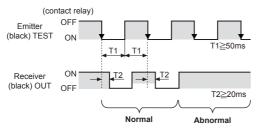
### © Emitter OFF (external diagnosis)

When TEST input (black) of emitter is 0V, emitting stops and red LED of emitter flashes. By stopping the emitting while TEST input of emitter is 0V, it is noticeable whether sensor operates in order from the external system. (If the emitting stops, sensor is in light OFF status and control output of receiver turns OFF.)

#### • Connections for TEST input



#### • Control output pulse by TEST input



## © Self-diagnosis

The unit regularly executes self-diagnosis during operation. If error occurs, control output turns OFF and the operation indicator displays the status.

#### Diagnosis items

- · Emitter: ① Damage in light emitter
  - 2 Emitter failure (Time out)
  - ③ Malfunction of MASTER/SLAVE line (operation in MASTER)
- · Receiver: ① Damage in light receiver
  - 2 Control output over current
  - ③ Malfunction, disconnection, or circuit break of synchronous line.
- Operation indicator displays each diagnosis items in different way. Refer to " Operation Indicator".

#### Interference protection

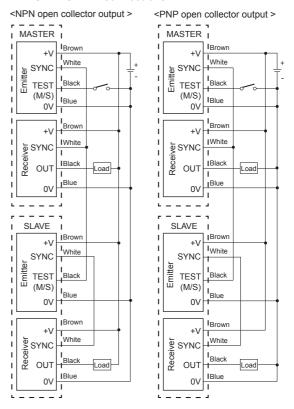
In case of using 2 sensors in parallel in order to extend sensing width, it may cause sensing error because as light interference.

This function is operating a sensor as MASTER and another sensor as SLAVE to avoid these sensing errors by the light interference.

#### • Time chart for MASTER/SLAVE transmission pulse



#### MASTER/SLAVE connections

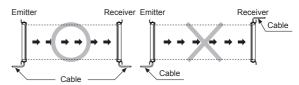


\*\*Connect 'TEST (M/S)' of SLAVE emitter to 'SYNC' of MASTER.

#### Installation

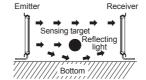
#### O For direction of installation

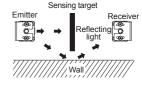
Emitter and receiver should be installed in same up/down direction.



## For reflection from the surface of wall and flat

When installing it as below the light reflected from the surface of wall and flat will not be shaded. Please, check whether it operates normally or not with a sensing target before using. (Interval distance: min. 0.5m)

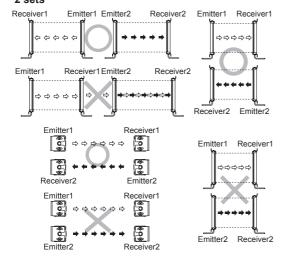




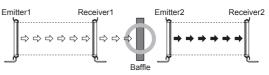
## O For prevention of interference

It may cause interference when installing more than 2 sets of the sensor. In order to avoid the interference of the sensor, please install as following figures and use the interference protection function.

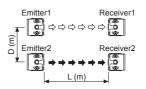
# Transmission direction should be opposite between 2 sets



#### . Baffle should be installed between 2 sets



#### • It should be installed out of the interference distance



Sensing distance (L)	Installation allowable distance (D)
0.1 to 3m	Min. 0.4m
Min. 3m	L×tan8°=min. L×0.14

\*\*There can be a little different based on installation environment.
\*\*Avoid using the unit in the place where the sensor is exposed directly to the fluorescent light with high speed start or high frequency.

## SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LiDAR

#### (D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

(G) Pressure Sensors

(H) Rotary Encoders

Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

# Operation Indicator

Item		Emitter Receiver					
		Indicator		Indicator		Control	
Item	illeiii		Red	Green	Yel- low	Red	output Light ON
Powe	r ON	≎	•	-	-	-	-
MAST	TER operation	ҏ	•	-	-	-	-
SLAV	E operation	<b>\rightarrow</b>	<b></b>	-	-	-	-
Test in	nput	<b>\rightarrow</b>	•	-	-	-	-
Break of emitter		$lackbox{1}{lackbox{1}{\mathcal{O}}}$	● ●	_	ı	-	-
Break	of light emitting element	▶	<b>④</b>	€	•	▶	OFF
<b>=</b> υ	Normal installation	•	•	≎	•	<b>①</b>	OFF
nstall	Hysteresis installation	•	1	•	≎	1	OFF
= =	Abnormal installation	•	1	•	•	1	OFF
Stable	e light ON	-	-	≎	•	•	ON
Unsta	ble light ON	-	-	≎	<b>\rightarrow</b>	•	ON
Unsta	ble dark ON	-	-	•	<b></b>	≎	OFF
Stable dark ON		-	-	•	•	≎	OFF
Break of receiver		-	-	$lackbox{1}{\circ}$	•	● ●	OFF
Control output overcurrent		-	-	€	<b>①</b>	≎	OFF
Synch	nronous line noise	-	-	<b>①</b>	•	<b>①</b>	OFF
Emitte	er failure (time out)	-	-	1	1	•	OFF

Display classification list	
<b>\rightarrow</b>	Light ON
	Light OFF
•	Flashing by 0.5 sec
① ① or ① ① ①	Flashing simultaneously by 0.5 sec
● ●	Cross-flashing by 0.5 sec
<b>(a) (b) (b)</b>	Sequence-flashing twice by 0.5 sec
	Cross-flashing twice by 0.5 sec

# Troubleshooting

Malfunction	Cause	Troubleshooting
Manufiction	Cause	
	Power supply	Supply the rated power.
Not operating	Incorrect cable connection or disconnection	Check the wiring.
	Rated connection failure	Use it within rated sensing distance.
	Pollution by dirt of sensor cover	Remove dirt by soft brush or cloth
Not operating sometimes	Connector connection failure	Check the assembled part o the connector.
	Out of rated sensing distance	Use within the rated sensing distance.
Control output is OFF even though there is no target object.	There is an obstacle to cut off the light emitted between emitter and receiver	Remove the obstacle.
terget object.	There is a strong electric wave or noise generated by motor, electric generator, high voltage line etc.	Put away the strong electric wave or noise generator.
LED displays for break of light emitting element	Break of light emitting element	
LED displays for failure of emitter	Break of light emitting circuit	Contact Autonics Corp.
LED displays for failure of receiver	Break of light emitting receiving element	
LED displays for	Synchronous line incorrect connection or disconnection	Check the wiring.
synchronous line	Break of synchronous circuit of emitter or receiver	Contact Autonics Corp.
LED displays for control	Control output line is shorten	Check the wiring.
output over current	Over load	Check the rated load capacity.
LED displays for emitter malfunction	Emitter malfunction	Treat after checking the emitter display LED.

Autonics D-49

# **BW Series**

## Proper Usage

- 1. Follow instructions in 'Proper Usage'.
  - Otherwise, It may cause unexpected accidents.
- 2. 12-24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- 3. Use the product, 1 sec after supplying power.
  - When using separate power supply for the sensor and load, supply power to sensor first.
- 4. When using switching mode power supply to supply the power, ground F.G. terminal and connect a condenser between 0V and F.G. terminal to remove noise.
- 5. When connecting a DC relay or other inductive load, remove surge by using diodes or varistors.
- 6. Wire as short as possible and keep away from high voltage lines or power lines, to prevent surge and inductive noise.
- 7. This unit may be used in the following environments.
  - ①Indoors (in the environment condition rated in 'Specifications')
  - ②Altitude max. 2,000m
  - 3 Pollution degree 2
  - 4 Installation category II

D-50 Autonics